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# Calibrating Time Domain Reflectometers for Soil Moisture Measurements in Sandy Soils<sup>1</sup>

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### Introduction

Soil moisture is a key factor for many agricultural processes, such as evapotranspiration, crop growth, and yield. It can be measured with either destructive (gravimetric) or nondestructive methods (soil moisture sensors) (Schmugge, Jackson, and McKim 1980). Soil moisture sensors such as time domain reflectometers (TDRs) allow for continuous, automated measurements. These sensors can be used by farmers to improve irrigation efficiency (Muñoz-Carpena and Dukes 2005), which in turn leads to reduced production cost by lowering water use. The Campbell Scientific CS616 Water Content Reflectometer, a type of TDR sensor, uses a quadratic calibration equation to acquire volumetric soil moisture (VSM). The reflectometers provide soil moisture measurements with accuracies of  $\pm 0.025$  m<sup>3</sup>m<sup>-3</sup> for certain soil properties and VSM ranges using the manufacturer-provided calibration curves (Campbell 2006). Since the sensor's output is not only dependent on the water content, but also on the physical and chemical properties of the soil, a soil-specific calibration is required to maximize accuracy for different soil types. The sensor calibration conducted in the laboratory with well-controlled water inputs and temperature is more accurate than the on-site

calibration procedure (Kinzli, Manana, and Oad 2012). In laboratory procedures, a container is packed with soil, but variations exist in the methods used to add or remove water to or from the soil (Young et al. 1997; Quinones, Ruelle, and Nemeth 2003; Regalado et al. 2003). However, implementing these methods for sandy soils is challenging due to high drainage rates and difficulties in maintaining a uniform distribution of water in the soil column.

In this publication, we describe a calibration protocol for a widely used TDR sensor, the Campbell Scientific CS616 Water Content Reflectometers specific for sandy soils, which are the most predominant soil type in Florida. The goal of this work is to provide accurate calibration coefficients for soil moisture measurements in Florida. The objectives are to (1) develop a sensor calibration protocol specific for sandy soils, (2) develop a calibration curve using the protocol, and (3) demonstrate the implementation of the calibration curve for the soil moisture measurements during the Eleventh Microwave Water and Energy Balance Experiment (MicroWEX-11) (Bongiovanni et al. 2015) conducted in the UF/IFAS Plant Science Research and Education Unit (PSREU) in Citra, FL. A comparison of

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VSM using the laboratory-calibrated and the manufacturersupplied coefficients shows the impact on soil moisture estimation.

## Campbell Scientific CS616 Water Content Reflectometer

The Campbell Scientific CS616 Water Content Reflectometer has two 30 cm-long stainless steel rods that are connected to a circuit board, as shown in Figure 1. An electromagnetic pulse propagates along the rods and is reflected back when the signal reaches the end of the rods. Another pulse is then sent as soon as the reflected pulse reaches the circuit board. The number of pulses received in a given amount of time (frequency [F]) is scaled down to a frequency that is measurable using a data logger. The travel time of the signal depends on the water content and the soil medium surrounding the rods. The time required between two pulses is the output period ( $\tau$ =1/F), and it is the raw output of the TDR sensor, as shown in Figure 2. The output period is converted to volumetric water content using the following calibration equation,

$$VSM = C_0 + C_1 + *\tau + C_2 *\tau^2 (1)$$

where  $C_0$ ,  $C_1$ , and  $C_2$  are calibration coefficients and  $\tau$  is the output period in  $\mu$ s. The manufacturer-specific accuracy for mineral soils (sandy loam and coarser) in the moisture range of 0.0–0.50 m<sup>3</sup>m<sup>-3</sup> is  $\pm$  0.025 m<sup>3</sup>m<sup>-3</sup> when the bulk electrical conductivity is less than 0.5 ds m<sup>-1</sup> and a bulk density is less than 1.55 g cm<sup>-3</sup>. The manufacturer-specific calibration coefficients for the CS616 sensor in mineral soils are listed in Table 1.



Figure 1. Campbell Scientific CS616 Water Content Reflectometer. Credits: Pang-Wei Liu, UF/IFAS



Credits: Tara Bongiovanni, UF/IFAS

Coefficient	Value		
Co	-0.0663		
C <sub>1</sub>	-0.0063		
C <sub>2</sub>	0.0007		
Source: Campbell Scientific 2006			

## **Field Site**

The soil samples were obtained from the upper 30 cm from the field site at the UF/IFAS Plant Science Research and Education Unit (29.41° N, 82.18° W). The soils at the site are Millhopper fine sand where the bulk density of the soil is 1.6 g cm<sup>-3</sup> with a sand, silt, and clay percentage of 92.59%, 1.97%, and 3.94% respectively and an organic matter content of 1.5%.

# **Calibration Protocol**

#### **Materials**

Table 2 provides a list of materials used for the sample preparation and calibration.

# Table 2. Materials needed for the sample preparation and calibration.

Sample Preparation	8-in square baking pans; oven; 2-mm sieve; bucket; 8,370 cm <sup>3</sup> of soil (after sifting); 2,502 mL of water.
Calibration	Campbell Scientific CR10X series data logger; computer; CS616 Water Content Reflectometer (Figure 1); chamber built using a 6-in diameter PVC pipe with 10-cm delineations (Figure 3); bucket; disk to compact soil into chamber (Figure 4); graduated cylinder; drill for mixing; 2,502 mL of water; 8,370 cm <sup>3</sup> of soil (after sifting).

#### **Soil Sample Preparation**

- Place soil samples of 8,370 cm<sup>3</sup> each into aluminum or tin baking pans and dry them in the oven at 100°C for 24 hours.
- Cool each sample and sift with the 2-mm sieve into an empty bucket.



Figure 3. Schematic of soil chamber with CS616 sensor. Credits: Pang-Wei Liu, UF/IFAS



Figure 4. Disk. Credits: Johanna Montanez, UF/IFAS

#### Calibration

- The calibration is performed in an environmentally controlled room held at a constant temperature of 24°C.
- Pour the sifted soil into a soil chamber (see Figure 3), using a disk to compact the soil every 10 cm.
- Repeat the process until the 40 cm mark has been reached, as shown in Figures 5 and 6.
- Insert the CS616 sensor vertically into the soil until the rods are completely immersed, as shown in Figure 7(a).
- Record output periods using a data logger and a computer (see Figure 7[b] and [c]) every minute for 10 minutes for a total of 10 measurements.

- After every 10-minute measurement, empty the soil into a clean bucket and add 420 mL of water. This amount equals 0.05  $m^3m^{-3}$  of water.
- Mix the sample thoroughly with a large drill as shown in Figure 8 and return the soil to the chamber, taking care to prevent loss of soil volume.
- Re-insert the CS616 sensor and rerun the experiment for another 10 minutes for an additional 10 measurements at the new moisture value. After each 10-minute measurement, repeat the process until saturation is reached.



Figure 5. Chambers with 10-cm delineations. Credits: Johanna Montanez, UF/IFAS



Figure 6. Compacting soil. Credits: Johanna Montanez, UF/IFAS







Figure 7. Schematic of calibration setup including (a) soil chamber with CS616 sensor and (b and c) data logger setup. Credits: Tara Bongiovanni, UF/IFAS



Figure 8. Mixing soil. Credits: Johanna Montanez, UF/IFAS

### **Correcting for Change in Soil Volume**

When water is added during each 10-minute experiment, the volume of soil changes compared to the original soil volume, as also observed by Kim et al. (2000). In order to account for the expansion or contraction of the soil, the actual volume of water added is determined by measuring the difference between the new and the original heights, as shown in Figure 9.

This procedure is repeated three times for different CS616 sensors (three in this publication for a total of nine calibration trials).



Figure 9. Displacement of the soil. Credits: Johanna Montanez, UF/IFAS

# **Calibration Coefficients**

Figure 10 shows the observed output period from the three sensors with respect to the controlled VSM compared with separate calibration curves for each sensor, the calibration curve obtained from the three sensors combined, and the manufacturer calibration curve. The observed output period from all three sensors follows a similar trend, with an inflection point around 0.10 m<sup>3</sup>m<sup>-3</sup> that could best be modeled using a third degree polynomial (Figure 10). It was found that implementing one curve for all sensors does not significantly reduce the quality of the estimate compared to using separate curves for each sensor, as shown in Table 3. This also shows no significant bias in between the three sensors indicating the reliability of sensor samples. Applying the new calibration, the root mean square error (RMSE) with respect to the actual soil moisture was 0.011 m<sup>3</sup>m<sup>-3</sup>. Table 4 shows the new calibration coefficients in Equation 2.

$$VSM = C_0 + C_1 + *\tau^2 + C_3 *\tau^3 (2)$$

Applying the standard calibration curve, the soil moisture was generally underestimated with an RMSE of 0.032 m<sup>3</sup>m<sup>-3</sup>, which is higher than the RMSE using the soilspecific calibration. Figure 11 compares the soil moisture derived from the manufacturer's standard calibration with that obtained using the new calibration. For soil moisture values below 0.022 m<sup>3</sup>m<sup>-3</sup>, soil moisture estimated with the standard calibration was higher than the soil-specific measurement, while the estimates were lower for values greater than 0.022 m<sup>3</sup>m<sup>-3</sup>. Figure 12 shows the mean and standard deviation of the curves for the separate sensors with an average regression error of 0.011 mm<sup>3</sup>m<sup>-3</sup> for soil moisture below 0.20 m<sup>3</sup>m<sup>-3</sup>. For moisture values above 0.385 m<sup>3</sup>m<sup>-3</sup>, the errors were greater than 0.02 m<sup>3</sup>m<sup>-3</sup>, primarily due to saturation limit for this soil. Figure 13 and Table 5 compare the soil moisture estimated using the standard and the soil-specific calibrations during the MicroWEX-11 bare soil experiment (Bongiovanni et al. 2015). The soil-specific calibration is generally higher than the standard calibration.



Figure 10. Volumetric soil moisture (VSM) as a function of output period for sensor calibration using standard coefficients, observations from separate sensors, and observations from all three sensors. Credits: Tara Bongiovanni, UF/IFAS



Figure 11. Comparison of calibration curves of volumetric soil moisture (VSM) using the standard calibration curve and the soil-specific calibration.

Credits: Tara Bongiovanni, UF/IFAS



Figure 12. Standard deviation of volumetric soil moisture (VSM) using the soil-specific calibration with respect to mean soil moisture. Credits: Tara Bongiovanni, UF/IFAS



Figure 13. Comparison of volumetric soil moisture (VSM) between the standard calibration and the soil-specific calibration during the MicroWEX-11 bare soil experiment. Credits: Tara Bongiovanni, UF/IFAS

Table 3. The RMSEs of VSM using coefficients from the standard, separate sensor, and all sensors calibrations for the individual sensor and the three sensors combined. Credits: Tara Bongiovanni, UF/IFAS

	Sensor 1 VSM (m <sup>3</sup> m <sup>-3</sup> )	Sensor 2 VSM (m <sup>3</sup> m <sup>-3</sup> )	Sensor 3 VSM (m³m⁻³)	Sensor 1–3 VSM (m <sup>3</sup> m <sup>-3</sup> )
Standard	0.027	0.031	0.038	0.032
Soil-specific: single sensor	0.011	0.007	0.007	0.011
Soil-specific: all sensors	0.011	0.008	0.012	0.011

Table 4. The calibration coefficients for VWC using all sensors. Credits: Tara Bongiovanni, UF/IFAS

Coefficient	Value
C <sub>o</sub>	-1.5377
C <sub>1</sub>	0.1814
C <sub>2</sub>	-0.007
C3	0.0001

Table 5. The mean and standard deviation of soil moisture during the MicroWEX-11 bare soil experiment. Credits: Tara Bongiovanni, UF/IFAS

	Standard Calibration		Soil-Specific Calibration	
Depth (cm)	μ VSM (m³m⁻³)	σ VSM (m <sup>3</sup> m <sup>-3</sup> )	μ VSM (m³m⁻³)	σ VSM (m <sup>3</sup> m <sup>-3</sup> )
2	0.049	0.014	0.068	0.021
4	0.055	0.019	0.077	0.030
8	0.072	0.016	0.102	0.022

## **Summary**

In this publication, we developed an in-laboratory calibration protocol for CS616 TDR sensors for sandy soils, which are typical of north central Florida. The soil-specific curve improved the RMSE by 0.02 m<sup>3</sup>m<sup>-3</sup> compared to the standard calibration curve. The soil-specific calibration coefficients were applied to TDR measurements at the depths of 2, 4, and 8 cm during the bare soil experiment in MicroWEX-11. The difference between the soil moisture using soil-specific calibration to that using the standard calibration was up to 0.06 m<sup>3</sup>m<sup>-3</sup>, which is significant enough to affect the predictions from hydrological and meteorological models (Entekhabi et al. 2014). The overall accuracy of soil-specific calibration curves is 0.011 m<sup>3</sup>m<sup>-3</sup>. However, when the soil moisture reaches 0.385 m<sup>3</sup>m<sup>-3</sup> and the sandy soils become saturated, the error increases to about 0.02 m<sup>3</sup>m<sup>-3</sup>.

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